# Efficient Construction of Hierarchical Overlap Graphs

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#### Outline

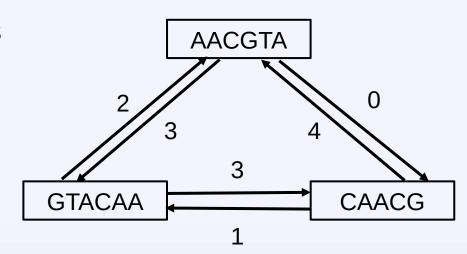
- Introduction
- Preliminaries
- Main algorithm
- Improvement using segment tree

#### Introduction

- Genome sequencing
  - DNA assembly: Obtaining a whole genome sequence from sequencing reads
  - Seeking some path in a graph that encodes suffixprefix overlaps
- Overlap encoding graphs
  - Overlap graph
  - De Bruijn graph

#### Introduction

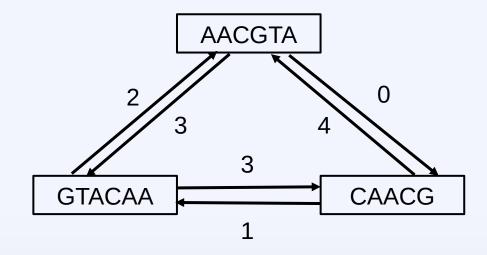
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# Shortest Superstring problem

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  - Let P be a set of input strings.
  - Find the shortest string that contains all input strings as substring.
- Equivalent to finding a maximum weighted Hamiltonian path in the overlap graph.
- Example P := { AACGTA, GTACAA, CAACG }

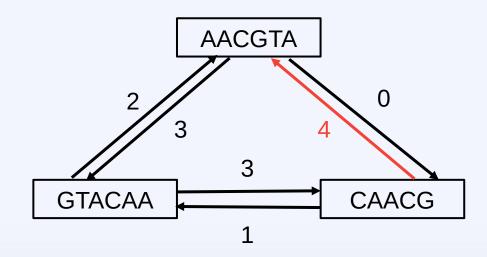
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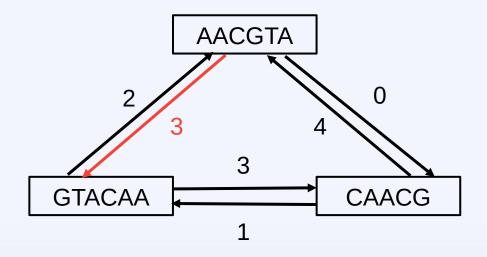
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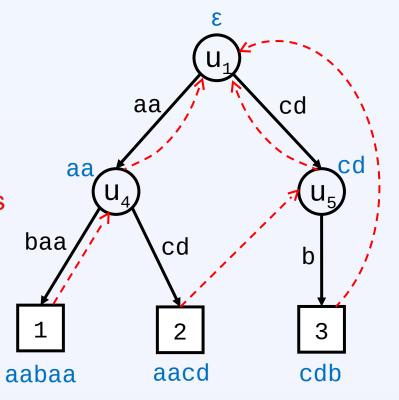
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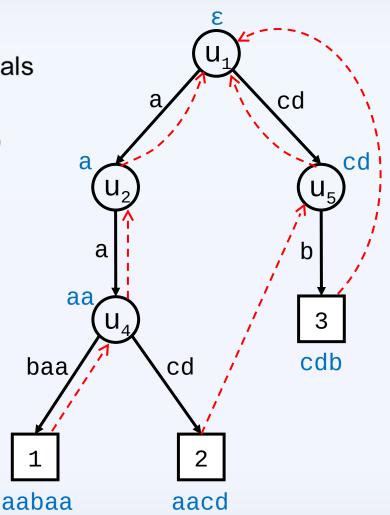
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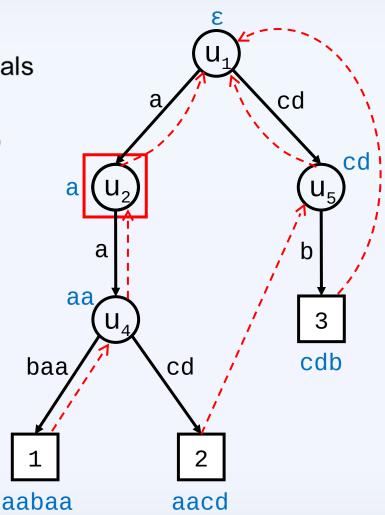
- Hierarchical overlap graph (HOG)
  - First proposed by Cazaux and Rivals
  - Given a set of strings,
    - Nodes: Maximal overlaps between strings
    - Arcs: Prefix or suffix relations between nodes
  - We can divide arcs into tree edges (prefix relations) and failure links (suffix relations).
- Example
  - $S = \{aabaa, aacd, cdb\}$



- Extended HOG (EHOG)
  - First proposed by Cazaux and Rivals
  - Given a set of strings,
    - Nodes: (Possibly not maximal)
       Overlaps between strings
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There are many advantages of HOG.

||P|| denotes the sum of lengths of strings in P

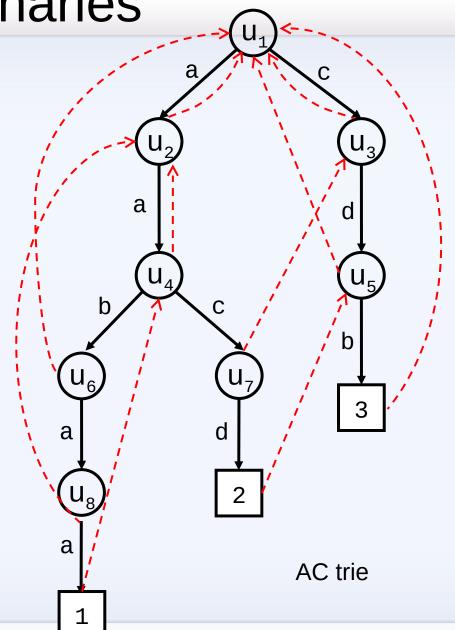
- HOG uses less space than overlap graph.
  - Overlap graph:  $O(||P|| + n^2)$
  - HOG: O(||P||)
- HOG has more information than the overlap graph.
  - HOG encodes a relationship between the overlaps.
     e.g. All identical overlaps are encoded into a unique node in HOG.
- HOG has a great potential in studying the shortest superstring problem.

#### **HOG:** construction

- EHOG can be constructed in O(||P||) time and space.
   (Cazaux B. and Rivals E., 2020)
- HOG uses more time and space.
  - Time:  $O(||P|| + n^2)$
  - Space:  $O(||P|| + n \times \min(n, \max\{|s|: s \in P)\})$ )
- We present an algorithm using less time and space.
  - Time:  $O(||P|| \log n)$  or  $O(||P|| \frac{\log n}{\log \log n})$
  - Space: O(||P||)

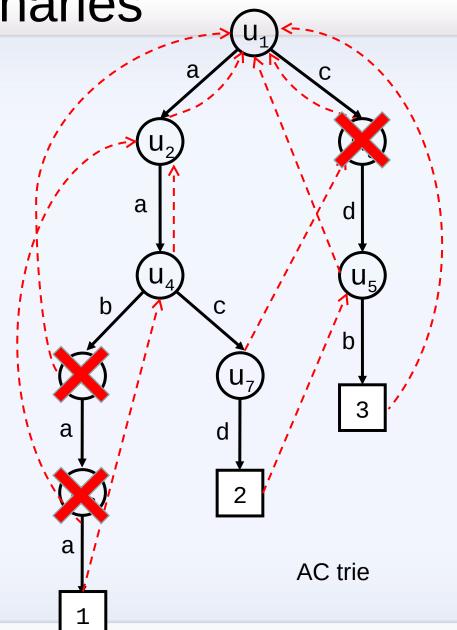
- Given a set of strings  $P = \{s_1, s_2, ..., s_n\}$ ,
  - $Ov^+(P)$ : Set of all overlaps from  $s_i$  to  $s_j$  for  $1 \le i, j \le n$
  - Ov(P): Set of the longest overlap from  $s_i$  to  $s_j$  for  $1 \le i, j \le n$
- In order to compute HOG, we need to compute Ov(P).
- If we have Ov(P) and EHOG(P), we can compute HOG(P) in O(||P||) time. (Cazaux B. and Rivals E., 2020)

- EHOG is a contracted form of an Aho-Corasick trie.
- HOG is a contracted form of an EHOG.
- Example
  - $-S = \{aabaa, aacd, cdb\}$

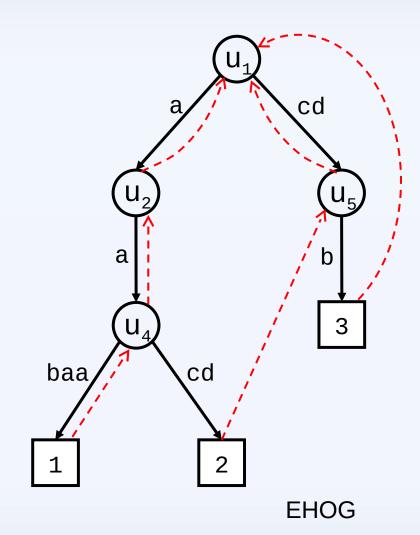


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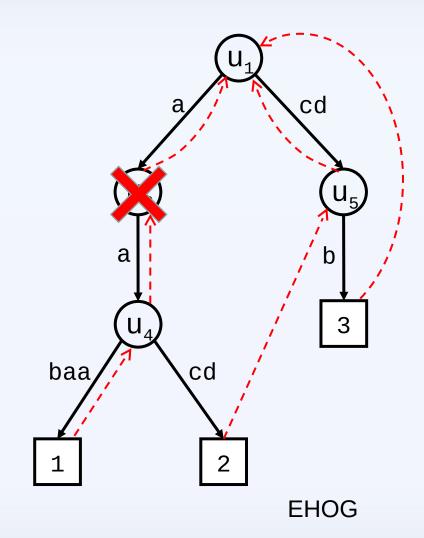
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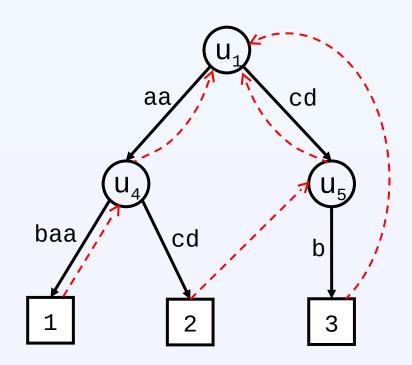
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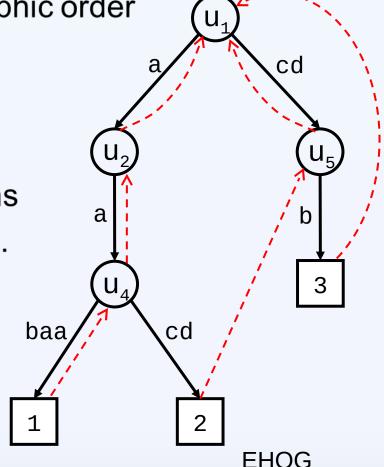
Build an Aho-Corasick trie of P

Renumber the strings in lexicographic order

• Build EHOG(P) in O(|P||) time

For each node u in EHOG(P),
 define an interval I(u) that contains
 every leaf node in the subtree of u.

• Example:  $I(u_1) = \{1, 2, 3\}$   $I(u_2) = \{1, 2\}$  $I(u_5) = \{3\}$ 



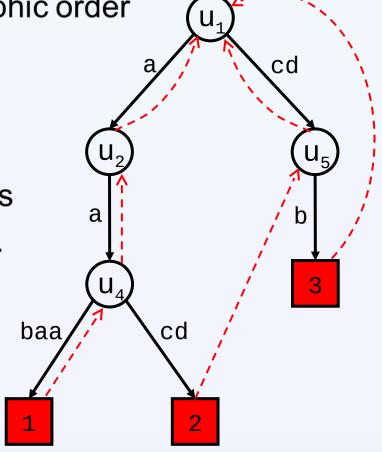
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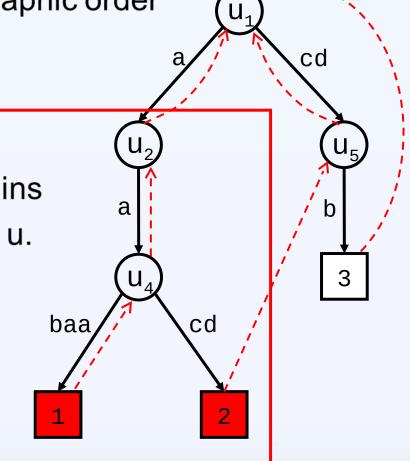
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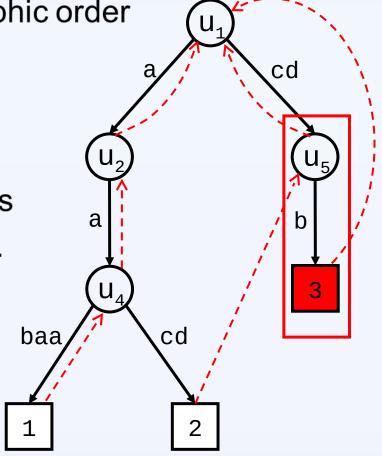
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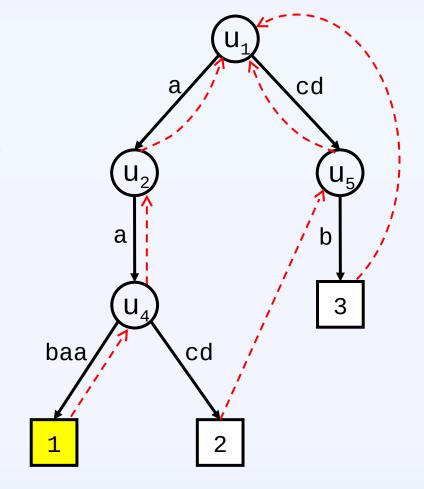
- We will compute Ov(P) from EHOG(P).
- What happens if  $u \in Ov(P)$ ?
- For some  $s_i, s_j \in P$ , u is the longest overlap from  $s_i$  to  $s_j$ .
  - u is a proper suffix of  $s_i$ .
  - u is a proper prefix of  $s_i$ .
  - There are no longer overlaps from  $s_i$  to  $s_j$  than u.

- If we follow the failure link from  $s_i$ , we get every suffixes of  $s_i$  in a decreasing order of lengths.
- If we have a failure link chain  $v_0 = s_i, v_1, v_2, ..., v_k = root$ ,  $v_x$  is the longest overlap from  $s_i$  to  $s_j$  if  $v_x$  is the first node that is a prefix of  $s_j$  during the traversal.
- In other words,  $v_x$  is the longest overlap from  $s_i$  to  $s_j$  if:
  - $v_x$  is a prefix of  $s_j$
  - $v_y$  is not a prefix of  $s_j$  for  $1 \le y < x$

- Maintain a bit vector B of length n.
- At the end of iteration with  $v_x$ , B[j] = true if and only if there exists  $1 \le y \le x$  such that  $v_y$  is a prefix of  $s_i$ .
- We can check whether  $v_x$  should be included in HOG(P) using B.

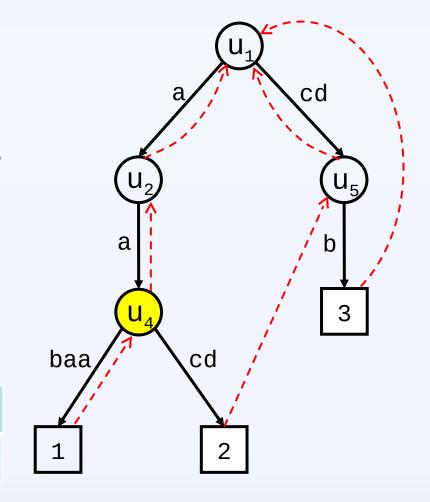
- We start with i = 1,  $s_i = aabaa$ .
- Initialize B with false.
- Follow the failure link repeatedly.

j	1	2	3
B[j]	false	false	false



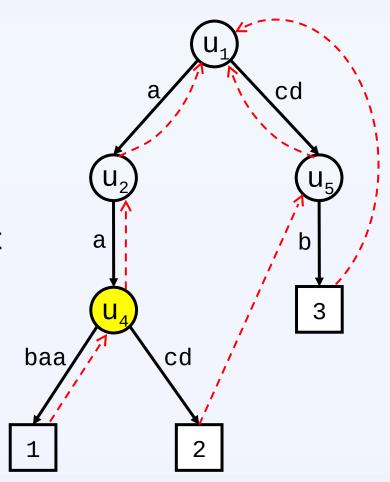
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- $v_1 = u_4$ :  $I(u_4) = \{1,2\}$

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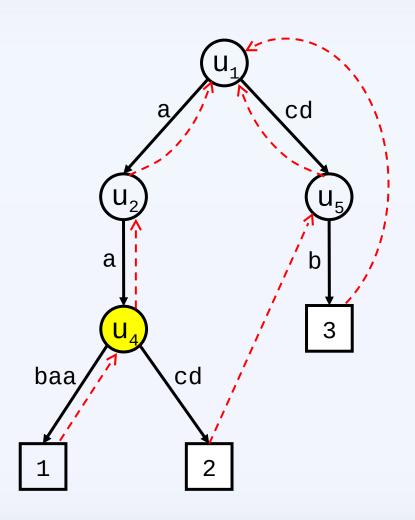
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- Initialize B with false.
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- $v_1 = u_4$ :  $I(u_4) = \{1,2\}$
- B[1] = B[2] = false:  $u_4$  is the longest overlap from  $s_1$  to  $s_1$  and  $s_2$ .

j	1	2	3
B[j]	false	false	false



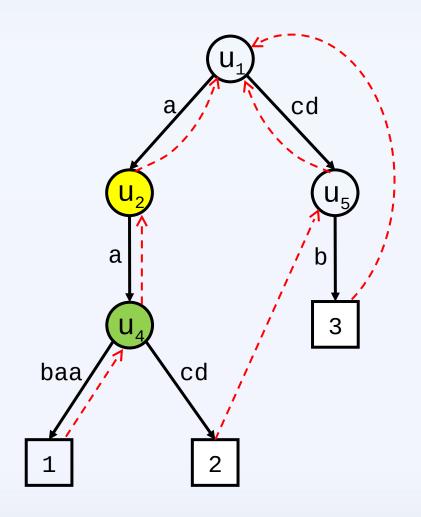
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- Initialize B with false.
- Follow the failure link repeatedly.
- $v_1 = u_4$ :  $I(u_4) = \{1,2\}$
- Update B[1] and B[2] as true.

j	1	2	3
B[j]	true	true	false



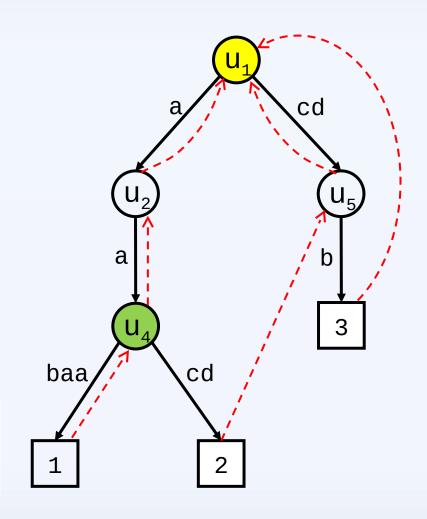
- We start with  $i = 1, s_i = aabaa$ .
- Initialize B with false.
- Follow the failure link repeatedly.
- $v_2 = u_2$ :  $I(u_2) = \{1,2\}$
- B[1] and B[2] are already true: u<sub>2</sub>
  is an overlap from s<sub>1</sub> to s<sub>1</sub> and s<sub>2</sub>,
  but not the longest one.

j	1	2	3
B[j]	true	true	false

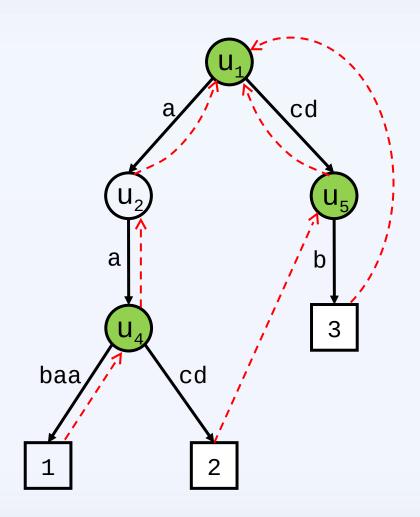


- We start with  $i = 1, s_i = aabaa$ .
- Initialize B with false.
- Follow the failure link repeatedly.
- $v_3 = u_1$ :  $I(u_1) = \{1,2,3\}$
- B[3] = false:  $u_1$  is the longest overlap from  $s_1$  to  $s_3$ .
- Update B[3] as true.

j	1	2	3
B[j]	true	true	true



- We start with  $i = 1, s_i = aabaa$ .
- Initialize B with false.
- We do the same procedure starting with  $s_2 = aacd$  and  $s_3 = cdb$ .
- $Ov(P) = \{u_1, u_4, u_5\}$

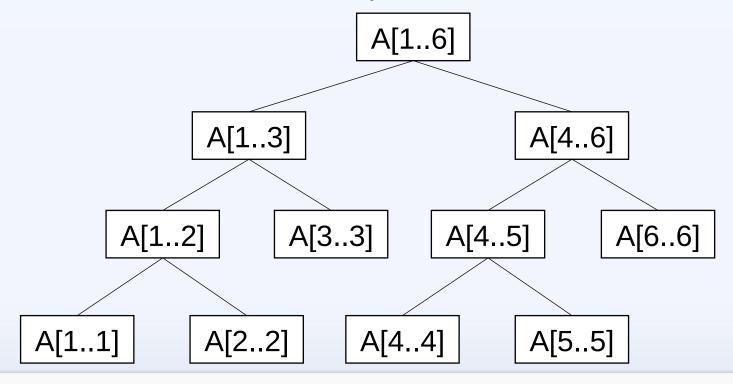


### Main Algorithm (summary)

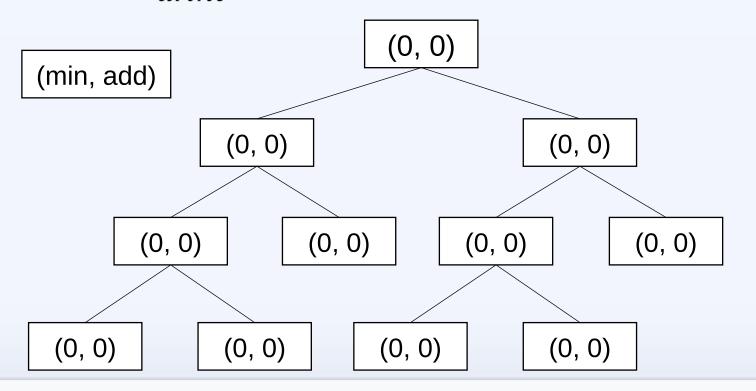
- For each  $s_i$ , do the following algorithm separately.
- Initialize B[1..n] to false
- Starting from node s<sub>i</sub>, follow the failure links while doing the following works:
  - i) If there exists  $j \in I(u)$  such that B[j] = false, mark u to be included in Ov(P).
  - ii) For  $j \in I(u)$ , update B[j] as true.
- Build a HOG with marked nodes and EHOG.

- We need to process these two types of queries on B:
  - i) If there exists  $j \in I(u)$  such that B[j] = false, mark u to be included in Ov(P).
  - ii) For  $j \in I(u)$ , update B[j] as true.
- Consider an integer array A and following queries on A.
  - i) Given an interval [a..b], compute the minimum value among A[a..b] (and check whether it is zero or not)
  - ii) Given an interval [a..b], add 1 to each element of A[a..b].
- $A[j] = 0 \leftrightarrow B[j] = \text{false}, A[j] > 0 \leftrightarrow B[j] = \text{true}$

- We use segment tree to process queries on A.
- Segment tree: A binary tree which has n leaf nodes and has O(log n) height.
- Each internal node u corresponds to an interval u.int

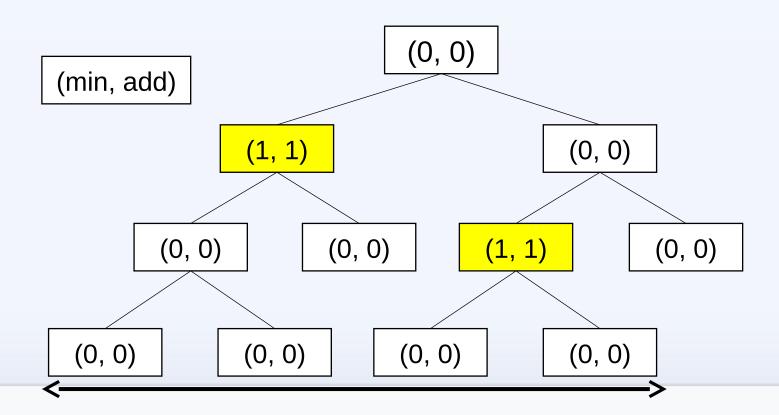


- Each node stores two values, min and add.
  - u.min: Minimum value among the elements in u.int
  - u. add : Collectively added value to the elements in u. int

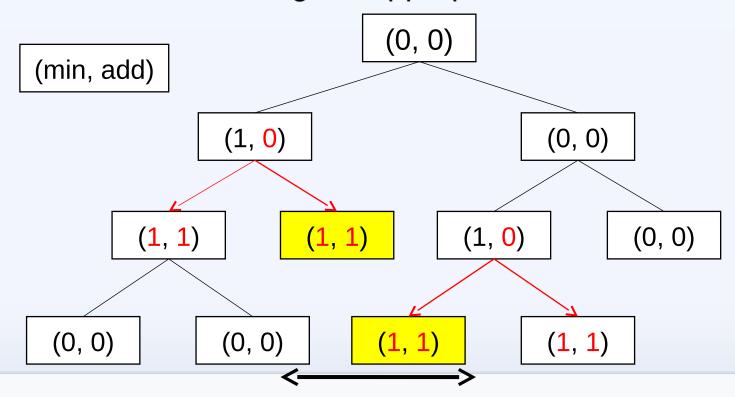


- We use lazy propagation technique.
- If query 1 occurs, we follow the nodes recursively from top to down, starting from the root.
- Considering a node u, we split the cases
- *u. int* is included in the query interval: return *u. min*
- u.int is disjoint with the query interval: return ∞
- Otherwise:
  - Propagate u. add to child nodes
  - Continue with child nodes, and return minimum among them.

- Example: Query 2 on A[1..5]
  - Update two nodes, representing A[1..3] and A[4..5]
  - Their children are not updated yet



- Example: Query 1 on A[3..4]
  - We get min from two nodes, A[3..3] and A[4..4]
  - add value of parent nodes are propagated to their child nodes, ensuring the appropriate min values.



- Any interval [a..b] can be represented by  $O(\log n)$  nodes in the segment tree.
- Both queries can be done in  $O(\log n)$  time.
- The total number of queries are O(||P||).
- Time complexity:  $O(||P|| \log n)$
- Both HOG and segment tree costs O(||P||) space.
- Space complexity: O(||P||)

#### Conclusion

- We have presented a new algorithm to compute HOG in  $O(||P||\log n)$  time and O(||P||) space, using segment tree.
- We improved the time complexity of our algorithm to  $O\left(||P||\frac{\log n}{\log\log n}\right)$ , using word RAM model / w-segment tree.

#### Open questions:

- can one get a linear time algorithm?
- can one extend the data structure to encode approximate overlaps?

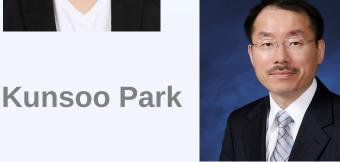
### Thanks for your attention



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**Bastien Cazaux** 



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- Improvement using word RAM model

### Improvement using word RAM

- Word RAM model: can read/write/do a bitwise operation for w-bit machine words in O(1) time. ( $w \ge \log n$ )
- By using bitwise operations, we can improve the running time of two queries from  $O(\log n)$  to  $O\left(\frac{\log n}{\log \log n}\right)$ .
- We use the w-segment tree, which is the w-ary version of the segment tree.

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### Improvement using word RAM

- Instead of *u.min* and *u.add*, we store two bit vectors of length *w*, *u.Vmin* and *u.Vadd*.
- If a node u is the j-th child of its parent p, p. Vmin[j] is true if and only if u. min = 0.
- We can update the w-segment tree similarly to the (binary) segment tree, but in  $O(\log_w n) = O\left(\frac{\log n}{\log\log n}\right)$  time.
- We can simulate w-segment tree using arrays, which results in using O(n) bits in total.

#### **Pointers**

Lazy Propagation in Segment Tree

https://www.geeksforgeeks.org/lazy-propagation-in-segment-tree/